

Context

- Sequence of random variable X_1, \dots, X_N
- Independent? $p(x_1, \dots, x_N) = p(x_1) \cdots p(x_N)$?
- Markov chain? $p(x_1, \dots, x_N) = p_1(x_1)p(x_1, x_2) \dots p(x_{N-1}, x_N)$ } short-range correlation.

- How to model long-range correlation?
- Matrix product ansatz : store hidden information
- Influence over the sum $S_N = X_1 + \dots + X_N$?

Definition

$$P(x_1, \dots, x_N) = \frac{\mathcal{L}(\prod_{k=1}^N \mathcal{R}(x_k))}{\mathcal{L}(\mathcal{E}^N)}, \quad S_N = \sum_{k=1}^N X_k$$

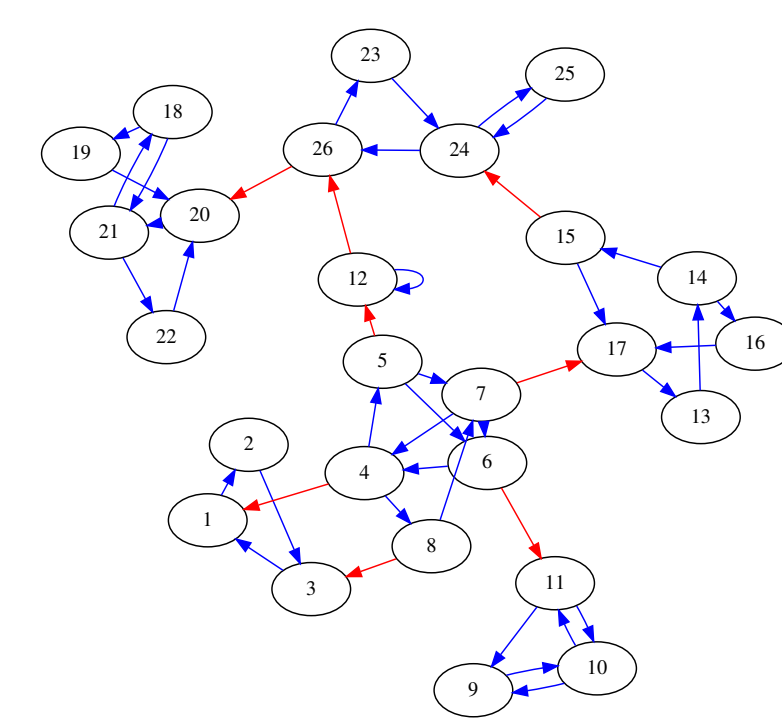
- $\mathcal{R}(x)_{i,j} = \mathcal{E}_{i,j} \mathcal{P}(x)_{i,j}$ $d \times d$ matrix
- \mathcal{P} : probability matrix
- $\mathcal{L}(M) = \text{tr}(A^T M)$: A positive matrix
- \mathcal{E} : positive matrix

Correlation

$$k < l, \quad \langle X_k X_l \rangle = \frac{\mathcal{L}(\mathcal{E}^{k-1} M(1) \mathcal{E}^{k-l-1} M(1) \mathcal{E}^{N-l})}{\mathcal{L}(\mathcal{E}^N)}, \quad M(q) = \int x^q \mathcal{R}(x) dx$$

- Graph representation $G(\mathcal{E})$ of \mathcal{E} :

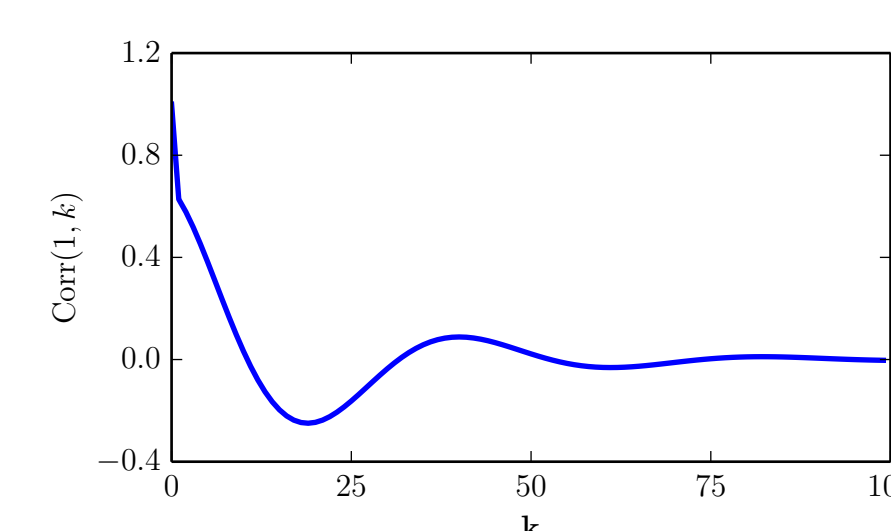
- Edge between i and j in $G(\mathcal{E}) \iff \mathcal{E}_{i,j} > 0$
- Graphical representation of the Markov chain transitions
- Two types of transitions : reversible and irreversible
- Irreversible transitions: ergodicity breakdown



- Reversible transitions:

- Short-range exponential correlation

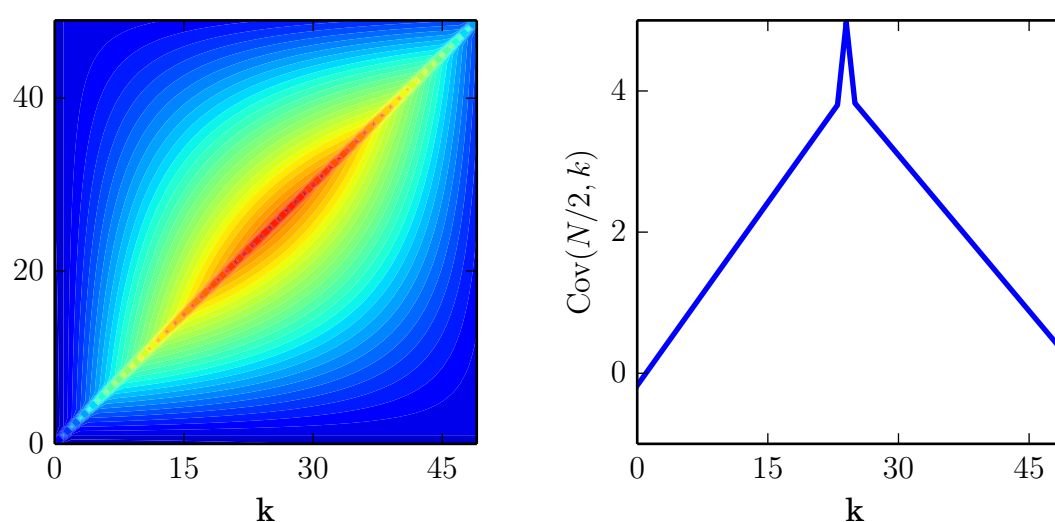
$$\langle X_k X_l \rangle \approx \sum c_e \left(\frac{\lambda_e}{\Lambda} \right)^{|k-l|}$$



- Irreversible transitions:

- Long-range piecewise polynomial covariance

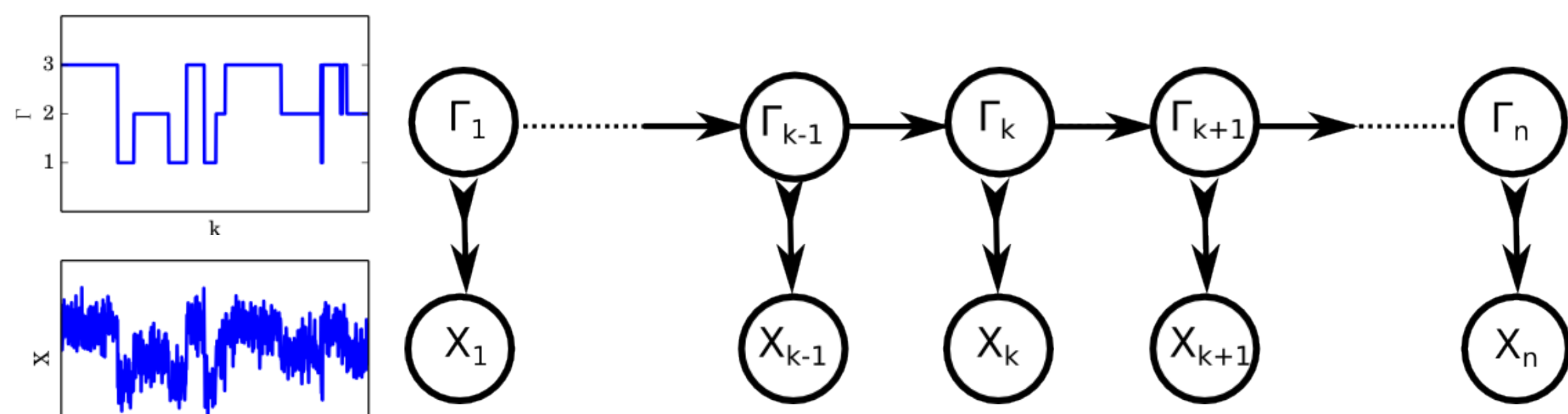
$$\langle X_k X_l \rangle \approx \sum_{r+s+t=\text{const}} c_{r,s,t} \left(\frac{k}{N} \right)^r \left(\frac{k-l}{N} \right)^s \left(1 - \frac{l}{N} \right)^t$$



Hidden Markov Model

- $X \implies (\Gamma, X)$: Separation of randomness into an observable level X and an hidden level Γ
- Γ : Hidden non-homogeneous Markov chain

$$P(\Gamma_1 = i, \Gamma_{N+1} = f) = \mathcal{A}_{if} \frac{(\mathcal{E}^N)_{if}}{\mathcal{L}(\mathcal{E}^N)} \quad P(\Gamma_{k+1} = j | \Gamma_k = i, \Gamma_{N+1} = f) = \mathcal{E}_{ij} \frac{(\mathcal{E}^{N-k})_{jf}}{(\mathcal{E}^{N-k+1})_{if}}$$

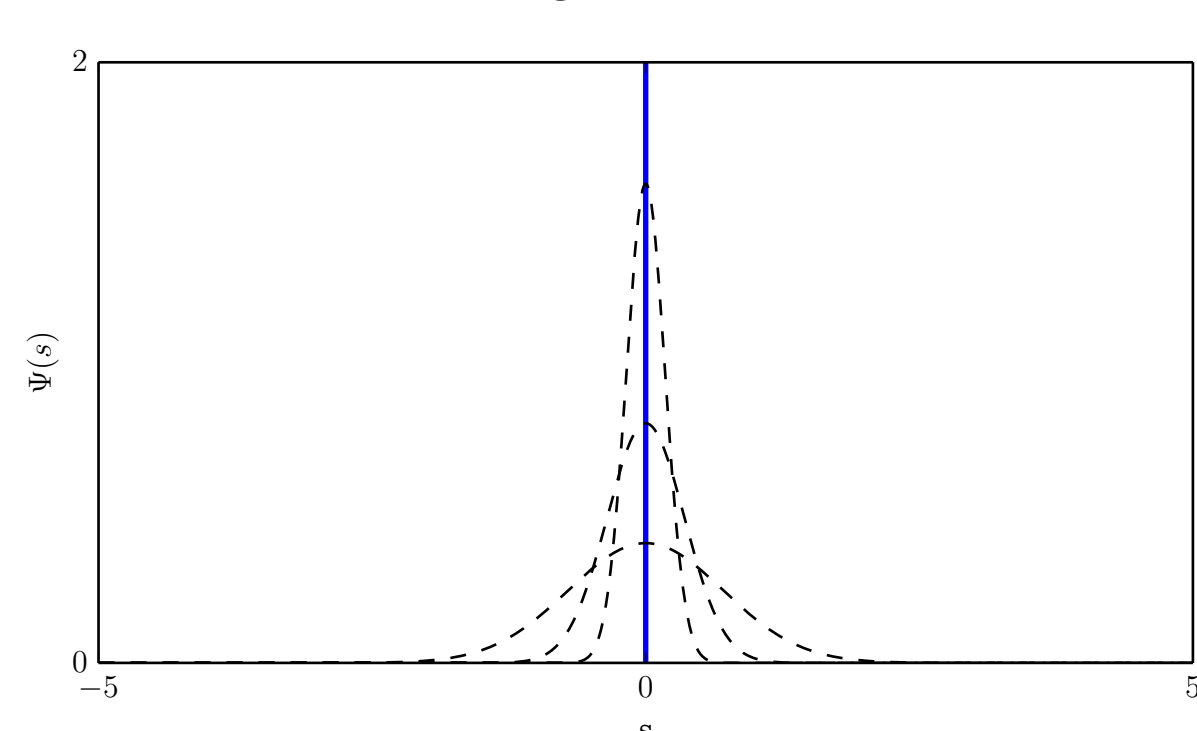


- Observable $\vec{X} = X_1, \dots, X_k$

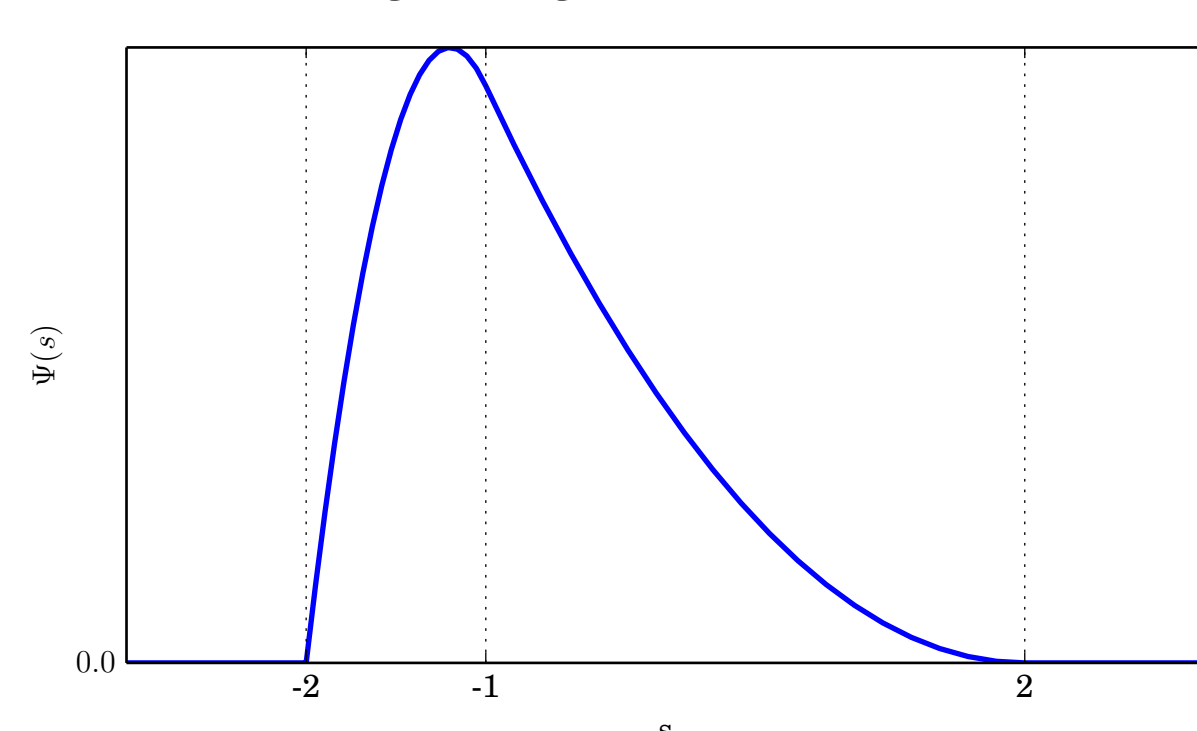
– $(X|\Gamma)_k$ are independent: $P(X_k = x | \Gamma) = \mathcal{P}_{\Gamma_k, \Gamma_{k+1}}(x)$

Generalized law of large numbers

Short-range correlation



Long-range correlation



- Law of large numbers for i.i.d. random variables:

$$\Psi(s) \equiv \lim_{N \rightarrow +\infty} p\left(\frac{S_N}{N} = s\right) = \delta(s - \mu), \quad \mu \in \mathbb{R}$$

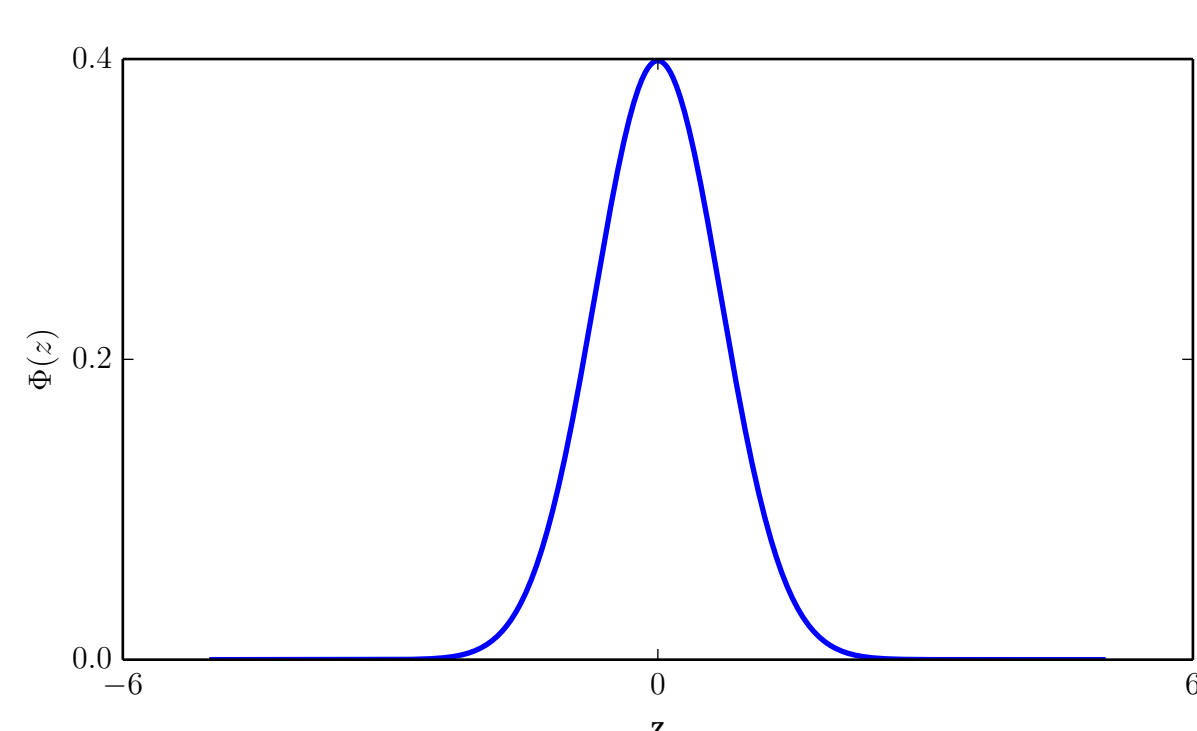
- Generalization of the law of large number : $\Psi(s)$ is no longer a Dirac

$$\Psi(s) = \sum_{\mathcal{E}} p(\mathcal{E}) \int \delta\left(\sum_{k=1}^{l_{\max}} \alpha_k - 1\right) \delta\left(s - \sum_{i,j=1}^{l_{\max}} \alpha_k \mu_{\mathcal{E}_k \mathcal{E}_k}\right) \prod_{k=1}^{l_{\max}} d\alpha_k,$$

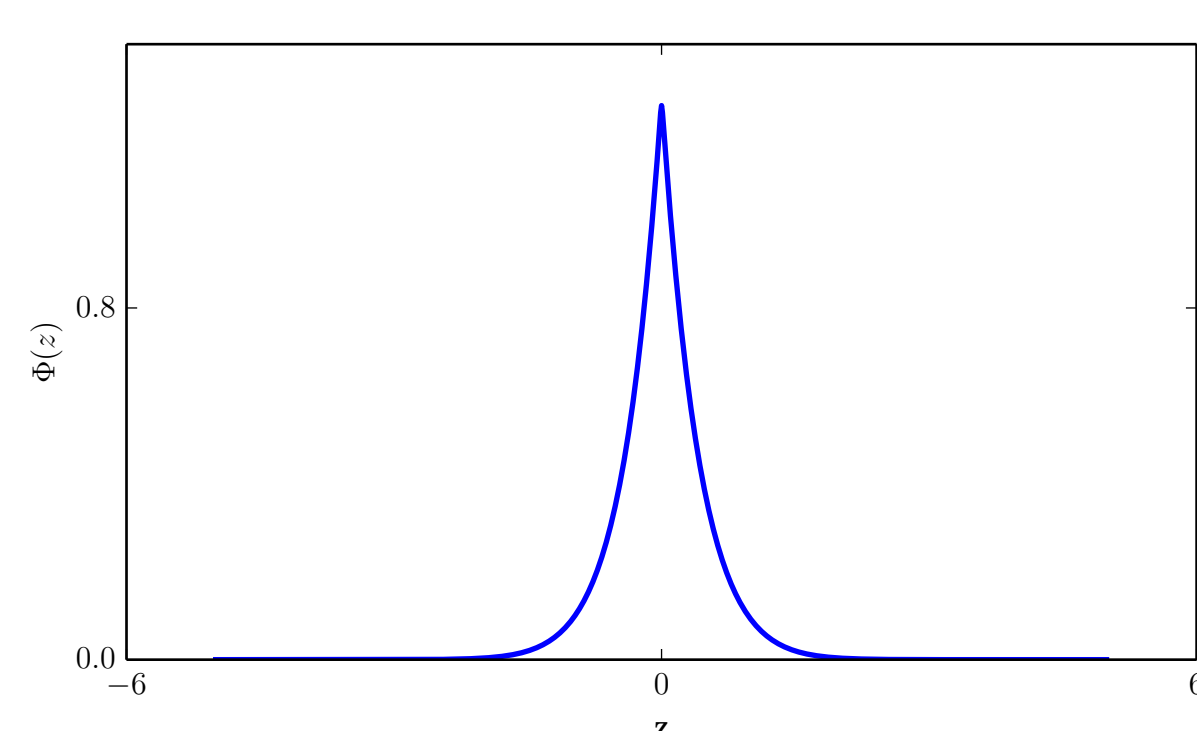
- $\Psi(s)$ is a piecewise polynomial

Generalized central limit theorem

Short-range correlation



Long-range correlation



- Central limit theorem for i.i.d. random variables

$$\Phi(z) \equiv \lim_{N \rightarrow +\infty} p\left(\frac{S_N - \mu N}{\sqrt{N}} = z\right) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-z^2/\sigma^2}$$

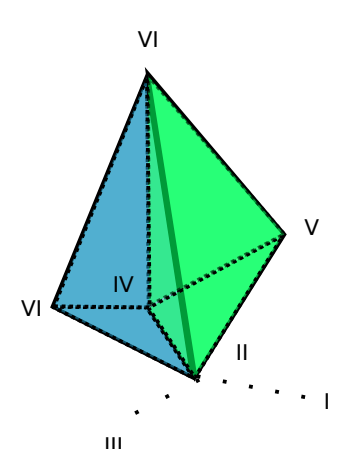
- Generalization of the central limit theorem : $\Phi(z)$ is no longer a gaussian

$$\Phi(z) = \sum_{\mathcal{E}} p(\mathcal{E}) \int \frac{\delta\left(\sum_{k=1}^{l_{\max}} \alpha_k - 1\right)}{\sqrt{2\pi \sum_{k=1}^{l_{\max}} \alpha_k \sigma_{\mathcal{E}_k}^2}} e^{-z^2/[2\sum_{k=1}^{l_{\max}} \alpha_k \sigma_{\mathcal{E}_k}^2]} \prod_{k=1}^{l_{\max}} d\alpha_k.$$

- $\Phi(z)$ is a discrete mixture of continuous mixture of centered gaussian

Constructive algorithm

- Exact computation of $\Psi(s)$
- Numerical computation of $\Phi(z)$
- Open source code on <https://github.com/FAngeletti/Pymatr>



Perspectives

- Sum for heavy-tailed distribution: what happens when $\langle X_k^2 \rangle = +\infty$?
- Extreme values statistics: limit distributions for $\max\{X_1, \dots, X_n\}$?
- Application to (TA)SEP: average number of particle?
- Inverse problem: how do we infer $(\mathcal{A}, \mathcal{E}, \mathcal{P})$ from observations?

References